**Examination:** May-June 2016 Date: 25-5-16 Branch: **Computer Engineering** Subject:

ΑI Class/SEM: BE/VII Paper Code: 21334

**Examination:** May-June 2016

Computer Engineering Subject: SC Branch:

Class/SEM: BE/VII Paper Code: 6000

Date:

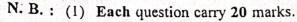
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Sub:-AI

QP Code : 31334

(3 Hours)

[ Total Marks : 80 ]



- (2) Question 1 is compulsory.
- (3) Attempt any three (3) from the remaining questions.
- (4) Assume suitable data wherever required.



- 1. Attempt any four (4) questions from the following:
  - (a) Draw and explain architecture of Expert System.
  - (b) Explain Hill-climbing algorithm with an example.
  - (c) Give PEAS description for a Robot Soccer player. Characterize its environment.
  - (d) Explain Turing test designed for satisfactory operational definition of intelligence.
  - (e) Prove that A\* is admissible if it uses a monotone heuristic.
  - (f) Compare and Contrast problem solving agent and planning agent.
- 2. (a) Explain decision tree learning with an example. What are decision rules?

  How to use it for classifying new samples?
  - (b) Write first order logic statements for following statements:
    - (i) If a perfect square is divisible by a prime p then it is also divisible by square of p.
    - (ii) Every perfect square is divisible by some prime.
    - (iii) Alice does not like Chemistry and History.
    - (iv) If it is Saturday and warm, then Sam is in the park.
    - (v) Anything anyone eats and is not killed by is food.
- 3. (a) Design a planning agent for a Blocks World problem. Assume suitable initial state and final state for the problem.
  - (b) Find the probabilistic inference by enumeration of entries in a full joint distribution table shown in figure 1.
    - (i) No cavity when toothache is there
    - (ii) p (Cavity! toothache or catch)

	toothache		¬toothache	
	catch	¬catch	catch	¬catch
cavity	.108	.012	.072	.008
cavity	.016	.064	.144	.576

Figure 1.

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- (a) Compare following informed searching algorithms based on 10
  performance measure with justification: Complete, Optimal, Time
  complexity and space complexity.
  - a) Greedy best first
  - b) A\*
  - c) Recursive best-first (RBFS)
  - (b) Apply alpha-Beta pruning on example given in Figure 2 considering first 10

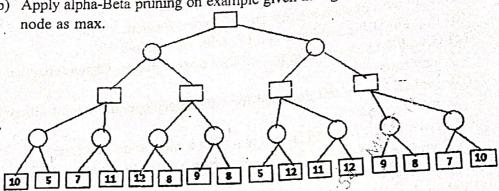


Figure 2.

- 5. (a) Explain how genetic algorithm can be used to solve a problem by taking a suitable example.
  - (b) Consider the graph given in Figure 3 below. Assume that the initial state is A and the goal state is G Find a path from the initial state to the goal state using DFS. Also report the solution cost

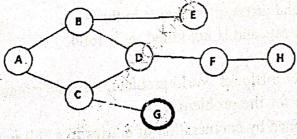


Figure 3.

- 6. (a) Explain the steps involved in converting the propositional logic 10 statement into CNF with a suitable example
  - (b) What are the basic building blocks of Learning Agent? Explain each of them with a neat block diagram.

QP Code: 6000

(3 Hours)

(Total Marks: 80

N.B. 1) Question No. 1 is compulsory

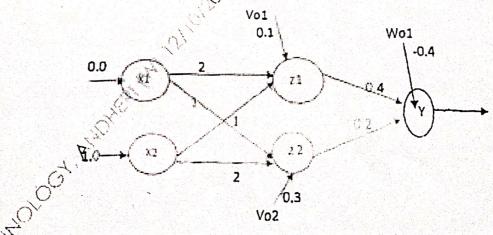
2) Attempt any three questions out of remaining 5 questions

3) Draw neat labeled diagram wherever necessary.

- A Define soft computing? Distinguish between soft computing and hard computing. Solve any four :
  - B Determine (alfa) a -level sets and strong a -level sets for the following fuzzy set.

 $A = \{(1, 0.2), (2, 0.5), (3, 0.8), (4.1), (5, 0.7), (6, 0.3);$ 

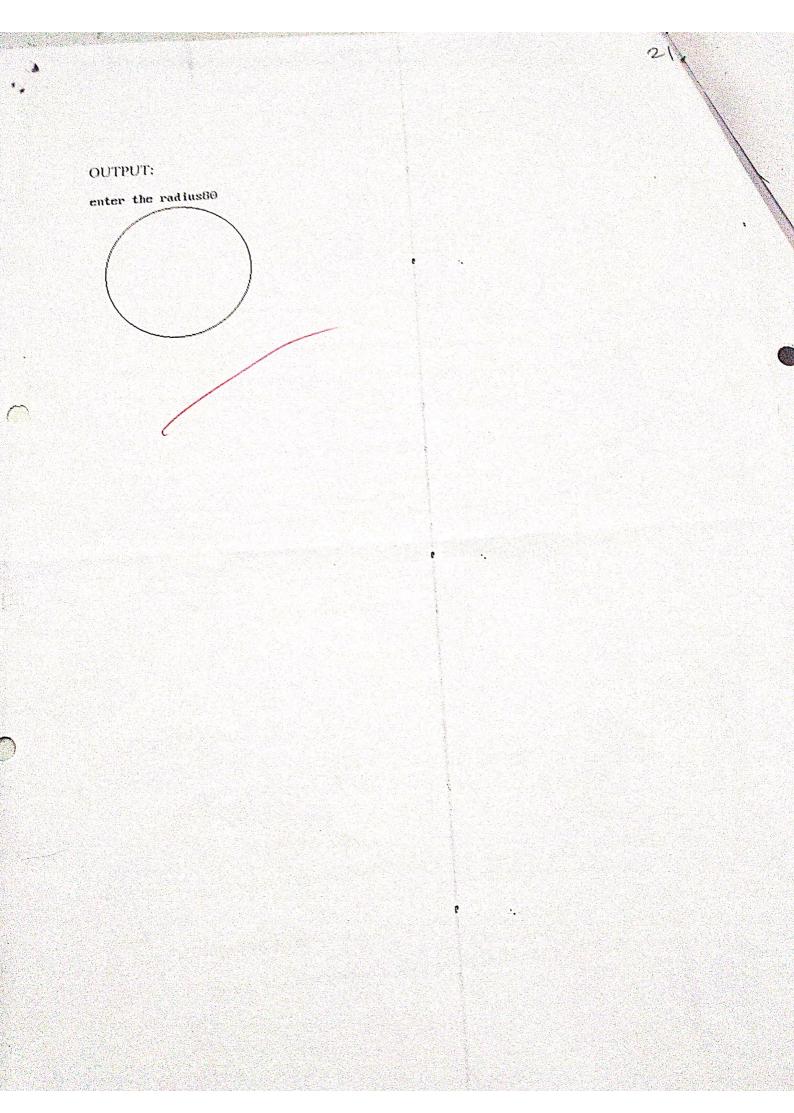
- Prove that the first order derivative of a unipolar continuous activation function f'(net) = 0(1-0)
- Draw the five layer architecture of ANFIS and explain each layer in brief. What are the differences between derivative free and derivative based optimization.
- Distinguish between Supervised and Un-supervised learning
- Design a fuzzy controller for a train approaching station. Inputs are speed and 20 Distance and output is Break power. Use triangular membership function. Consider two descriptor for Input and three descriptors for output. Derive a set of rules for control action and defuzzification. The design should be supported by figures wherever possible. Design a fuzzy controller for a train with high speed and small distance.
- 3 A Apply Backpropogation Algorithm to find the final weights for the following net. 10 inputs: x = [0.0,1.0], Weights between Hidden and Gutput Layers: w = [0.4,0.2], Blas on the Output Node O is Wo= [-0.4], Weights between Input and Hidden Layer: v = [2,1;1,2], Blas on Hidden Unit nodes are Vo=  $[0.1 \ 0.3]$ , [Restred output : d = 1.0,



- What is self-organizing map? Draw and explain architecture of Kohonen Self Organization Feature Map KSOFM.
- A. What are the different types of encoding, selection, crossover, mutations of GA. Explain 10 each type with suitable examples
  - Explain with suitable examples Linearly and Non-linearly separable pattern

10

10



A Explain Learning Vector Quantization Algorithm? QP Code: 6000 The formation of algal solutions in surface water is strongly dependent on pH of water, temperature and oxygen content. temperature and oxygen content. T is a set of water temperatures from a take given by C= (1. 2, 6). T= {50, 55, 60} and O is oxygen content. T is a set of water temperatures non.

The first (50, 55, 60) and O is oxygen content values in water given by O= {1, 2, 6}. 10 The fuzzy set of T is given by (0.7/50+0.8/55+0.9/60) and 10 fuzzy set of O is given by (0.1/1+0.6/2+0.8/6) I. Find R= $7 \times 0$  for Given  $I = \{0.5/50 + 1/55 + 0.7/60\}$ ii. Find S=1 o R using max-product composition lil. Find S= 1 o R using max-min composition 6 Write short notes on any two: Steepest Descent algorithm 20 **Newton Method** C Fuzzy inference system

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```
{
  y=y+,1;
  e=e-2*dx;
}

x=x+1;
e=e+2*dy;
putpixel(x,y,15);
i=i+1;
}
while(i<=dx);
getch();
}
OUTPUT:</pre>
```